

CSE-111 Great Ideas in Computer Science

Albert Y. C. Chen

University at Buffalo, SUNY

# **THINKING IN THE OBJECT ORIENTED WAY + A BRIEF INTRO TO CS RESEARCH**

# OVERVIEW

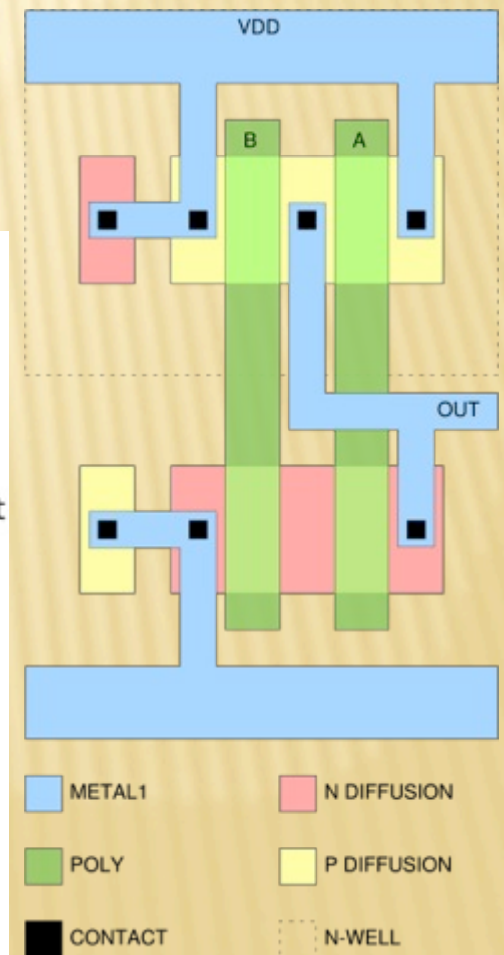
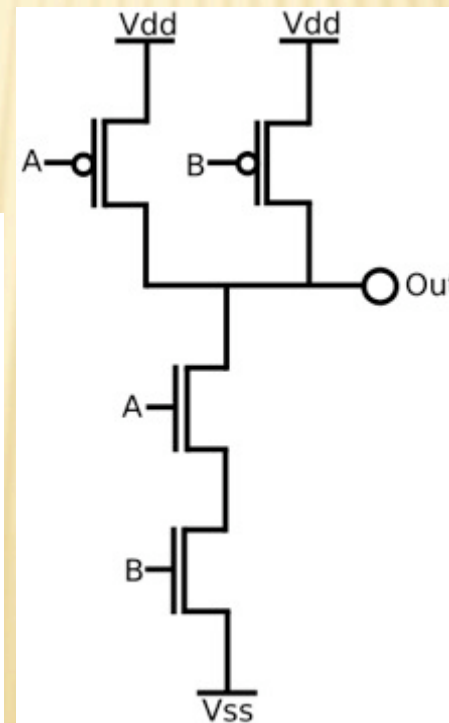
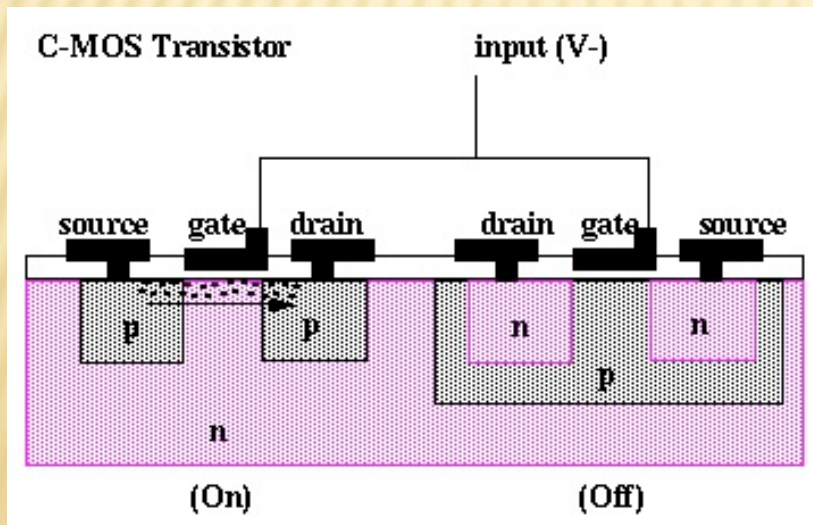
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- ✘ Finally, putting everything all together. Also, we'll learn how complicated things are simplified by thinking in the object oriented way.
  - + From logic gates to making CPUs!
  - + From machine language to Karel-the-robot to 3D dragon drawing using the concepts of OOP!!
- ✘ A gentle introduction to the fields of research in computer science.
  - + What can we do with all the powerful tools we have developed in the past few decades?

# LOGIC GATES

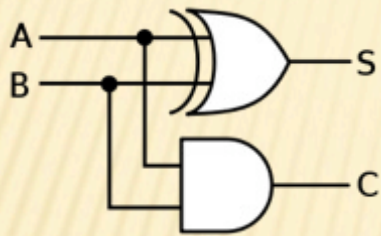


- ✘ How are logic gates implemented on “semi-conductors”?
- ✘ e.g. NAND gate using CMOS:

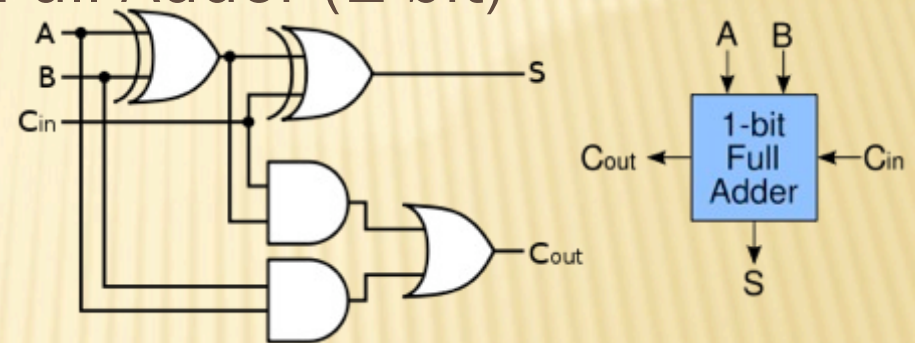


# LOGIC GATES → BASIC ARITHMETIC UNITS

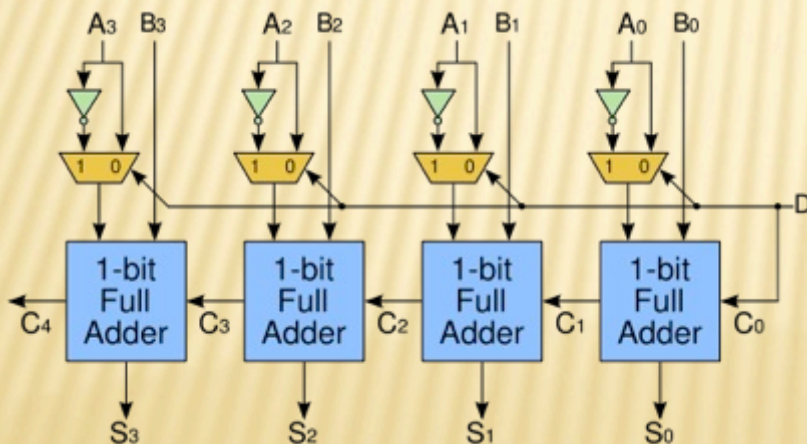
## ✘ Half Adder (1-bit)



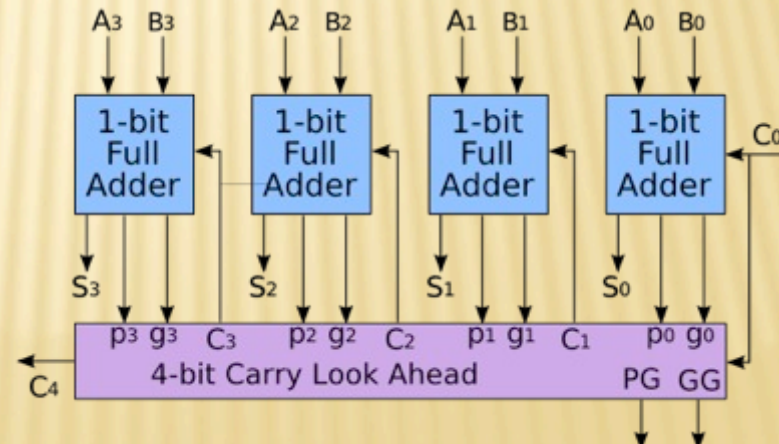
## Full Adder (1-bit)



## ✘ Ripple Carry Adder



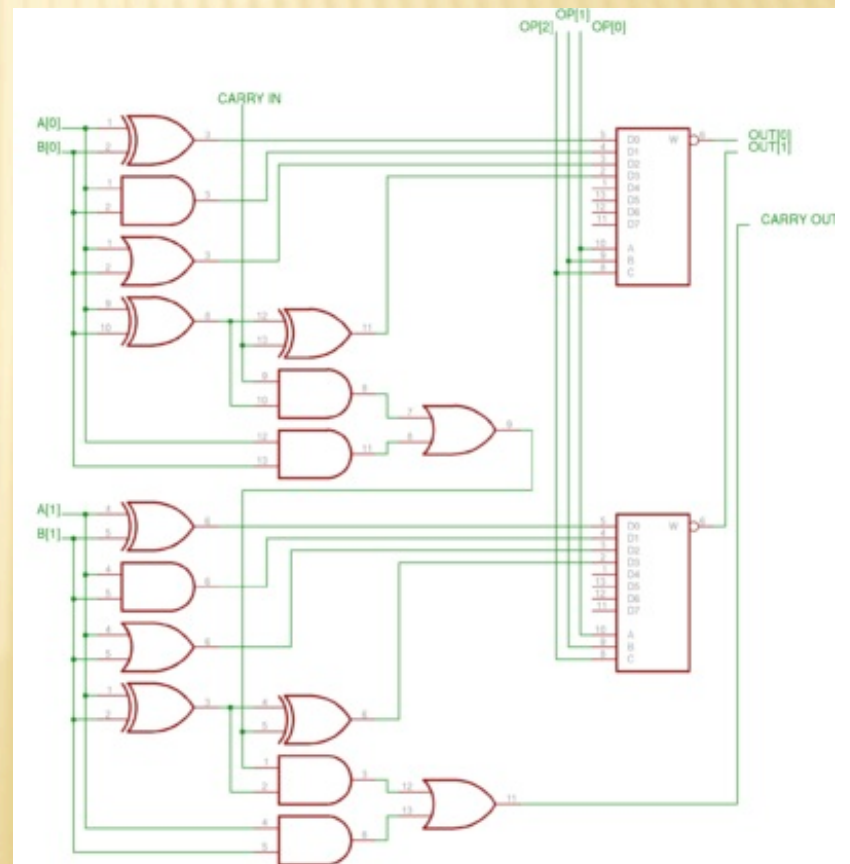
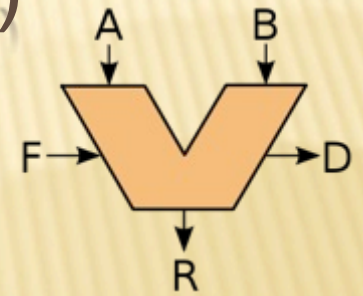
## Carry look-ahead Adder



# BASIC ARITHMETIC UNITS

## → ARITHMETIC LOGIC UNITS (ALU)

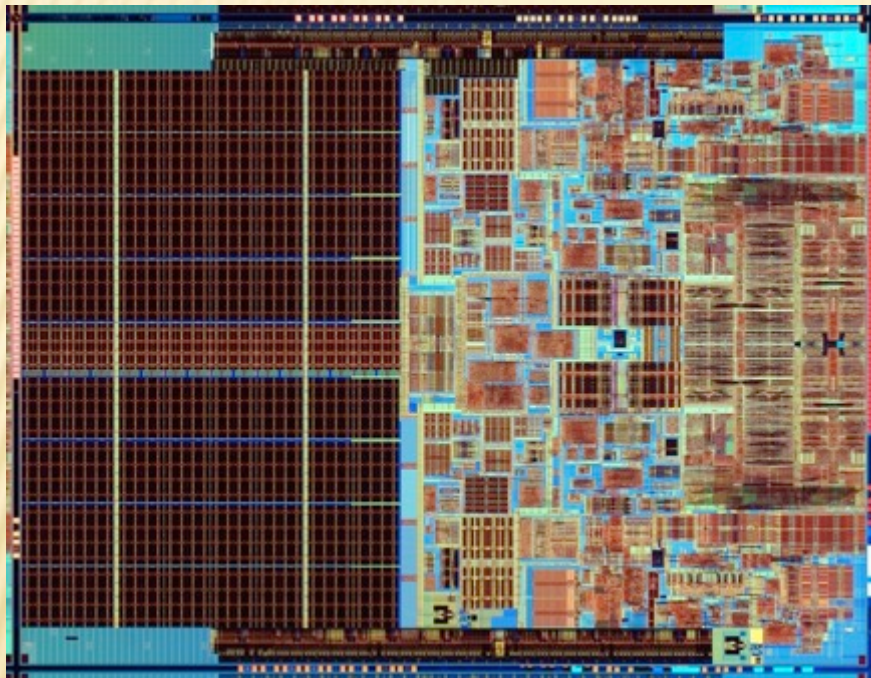
- ✘ ALU: Basic building block for computer's CPU (Central Processing Unit)
  - + Takes input **A**, **B**, then perform the operation according to the given instruction **F**.
    - ✘ Addition, subtraction
    - ✘ Multiplication, division (optional)
    - ✘ Bitwise Logic op. (AND, OR, NOT)
    - ✘ Bit shifting operations
  - + E.g. (right) 2 bit ALU that does XOR, AND, OR, addition.



# ARITHMETIC LOGIC UNITS (ALU)

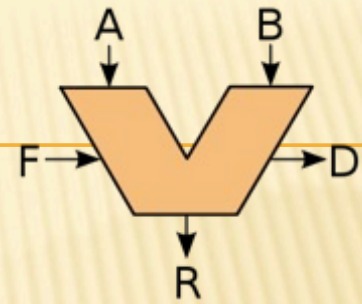
## → CENTRAL PROCESSING UNIT (CPU)

- ✘ The “die” of Intel’s Core 2 Duo (Conroe) CPU



- + With machines so complicated and powerful, how are we going to send instructions (the control signal “F” in the ALU example) to the ALU?

# INSTRUCTIONS FOR THE CPU?



- ✘ Starting with the 2 bit ALU.
  - + We can have 00, 01, 10, 11 four different kind of control signals, i.e. we can integrate 4 different operations into this ALU (e.g. F=00 XOR; F=01 AND; F=10 OR; F=11 addition).
  - + Examples
    - ✘ Suppose we want to perform  $A+B$ , where  $A = 00$  and  $B = 10$ , and suppose the instructions sent to the ALU are 6 Boolean digits of the order “2 bit command” “2 bit A” “2 bit B”.
    - ✘ We’ll look up the command for “+”, which is “11”, then write “110010” in our program as the instruction for the ALU.
    - ✘ When the ALU receives 110010, it will decode it and know that you want it to set  $F=11$  (which is to perform addition”, and the inputs are  $A = 00$ ,  $B = 10$

# INSTRUCTIONS FOR THE CPU?

- ✘ Are these four instructions sufficiently enough?
  - + Not actually, we'll also need instructions to:
    - ✘ Control flow instructions such as “if”, “else”.
    - ✘ Data control instructions to move things around in the memory.
- ✘ Should all commands be implemented in hardware?
  - + CISC (Complex Instruction Set Computer):
    - ✘ Powerful commands, yet takes longer for each command to be executed.
  - + RISC (Reduced Instruction Set Computer):
    - ✘ Simpler commands, each command runs faster, but may takes more commands to do a job.
  - + For example, a ALU only capable of doing “addition” can calculate “ $2 \times 5$ ” by doing “ $2+2+2+2+2$ ”.



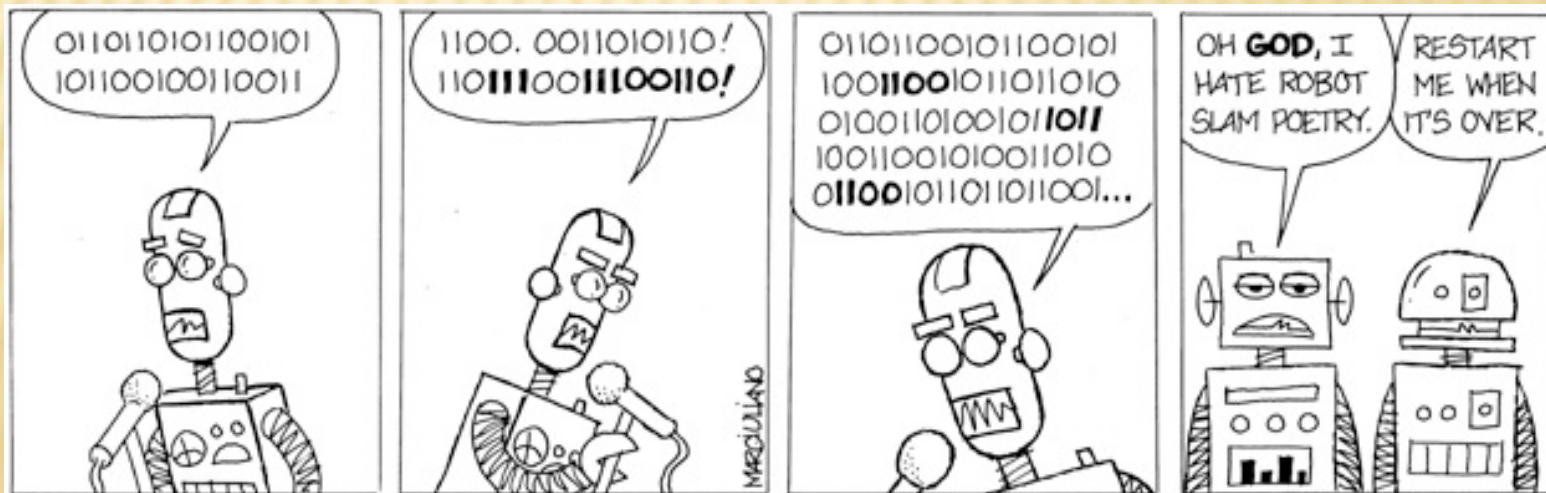
# 1<sup>ST</sup> GENERATION PROGRAMMING LANGUAGE

- ✘ Writing a program directly in CPU instructions:

01010010 11001011 10100101 000100100 10011010 ...

- + Ugh ... Can we write these in decimal or hexadecimal?
- + OK, here's the 32-bit x86 machine code (1<sup>st</sup> generation programming language) to calculate the nth Fibonacci number (i.e. 0,1,1,2,3,5,8,13,21,34,55,89,...)

8B542408 83FA0077 06B80000 0000C383 FA027706 B8010000 00C353BB  
01000000 B9010000 008D0419 83FA0376 078BD98B C84AEBF1 5BC3



## 2<sup>ND</sup> GENERATION PROGRAMMING LANGUAGE

- ✘ Instructions that we can finally remember (sort of...)
- ✘ Still “Machine Dependent”, thus still “low level”.
  - + i.e. code would need to be completely re-written whenever Intel or AMD introduces a new CPU...
- ✘ Fibonacci number calculator in MASM assembly language:

```
fib:                                @@:                                dec edx
    mov edx, [esp+8]                push ebx                            jmp @b
    cmp edx, 0                      mov ebx, 1
    ja @f                            mov ecx, 1                            @@:
    mov eax, 0                       @@:                                pop ebx
    ret                               @@:                                ret
@@:                                  lea eax, [ebx+ecx]
    cmp edx, 2                       cmp edx, 3
    ja @f                            jbe @f
    mov eax, 1                       mov ebx, ecx
    ret                               mov ecx, eax
```

# HIGH-LEVEL PROGRAMMING LANGUAGES (3<sup>RD</sup> GEN. AND BEYOND)

- ✘ Provides a higher level of abstraction from details of the computer (e.g. CPU commands, registers, ...etc.)
  - + Our Karel-the-robot language is high level.
    - ✘ So are Basic, C, C++, Java, Python, ... almost any programming language you can think of.
    - ✘ The term “high” doesn’t mean it’s superior to low level languages, its that it provides a higher level of abstraction.
  - + So, what’s the difference?
    - ✘ Instead of sending “11010101” or “mov edx [esp+8]”, we use commands that are very similar to plain English (if, else; while {...})
    - ✘ Instead of specifying which “CPU register” or “memory location” we’re going to access, we use “Variables” to store data.

# HIGH-LEVEL PROGRAMMING LANGUAGES

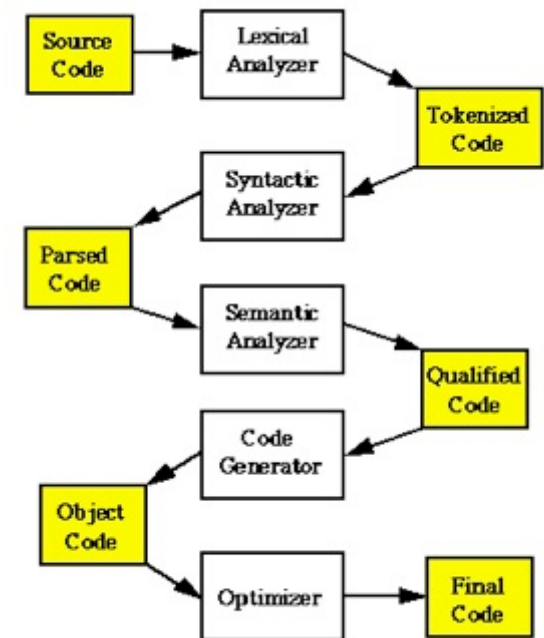
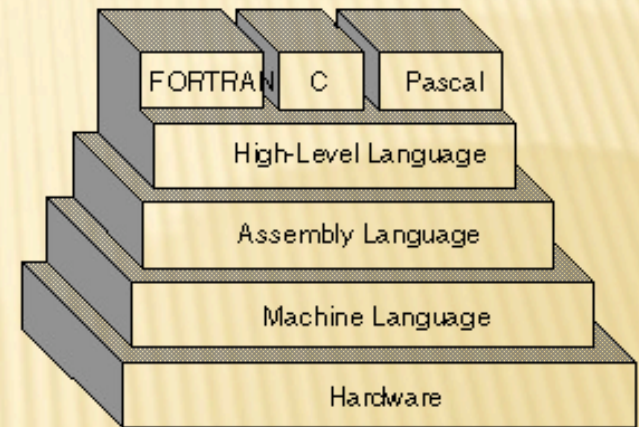
## – FIBONACCI NUMBERS REVISITED

- ✘ Fibonacci Numbers: 0,1,1,2,3,5,8,13,21,34,55,89,...
- + The  $N^{\text{th}}$  number is the sum of the  $(n-1)^{\text{th}}$  and  $(n-2)^{\text{th}}$  number
- ✘ Using Karel's parental language "Pascal":

```
program fibonacci
var
    NumOfFibs, i, prevNumOne, prevNumTwo, currentNumber : integer;
begin
    NumOfFibs := 10; i:=0; prevNumOne := 1; prevNumTwo := 0;
    writeln(prevNumTwo); writeln(prevNumOne);
    while i<NumOfFibs-2 do begin
        currentNumber := prevNumOne + prevNumTwo;
        writeln(currentNumber);
        i := i +1;
        prevNumTwo := prevNumOne;
        prevNumOne := currentNumber;
    end;
end;
```

# COMPILERS

- ✘ Compilers do all the hard work of translating programming languages to machine-specific instructions.
- ✘ When we write in Karel and hit the button “compile”, our code is examined by the compiler in the following order:
  - + Lexicons (the vocabulary we used, e.g. “if”)
  - + Syntax (e.g. missing “;”, “end;”)
  - + Semantic...
- ✘ A translator of this sort will be needed for every two layers in the programming language pyramid shown in the upper right figure.



# OBJECT ORIENTED PROGRAMMING (OOP)

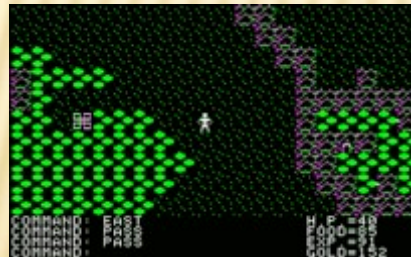
## ✘ Why OOP?

- + Hardware and software became increasingly complex.
- + To assure “quality” and “code re-usability”
  - ✘ It’s impossible for a 3D game developer nowadays to write codes for each pixel he/she wants to display on the screen – It will not only be slow, but also prone to error.

Spacewar! (1961)



Ultima1 (1980)



Doom (1993)



World of Warcraft (2004)



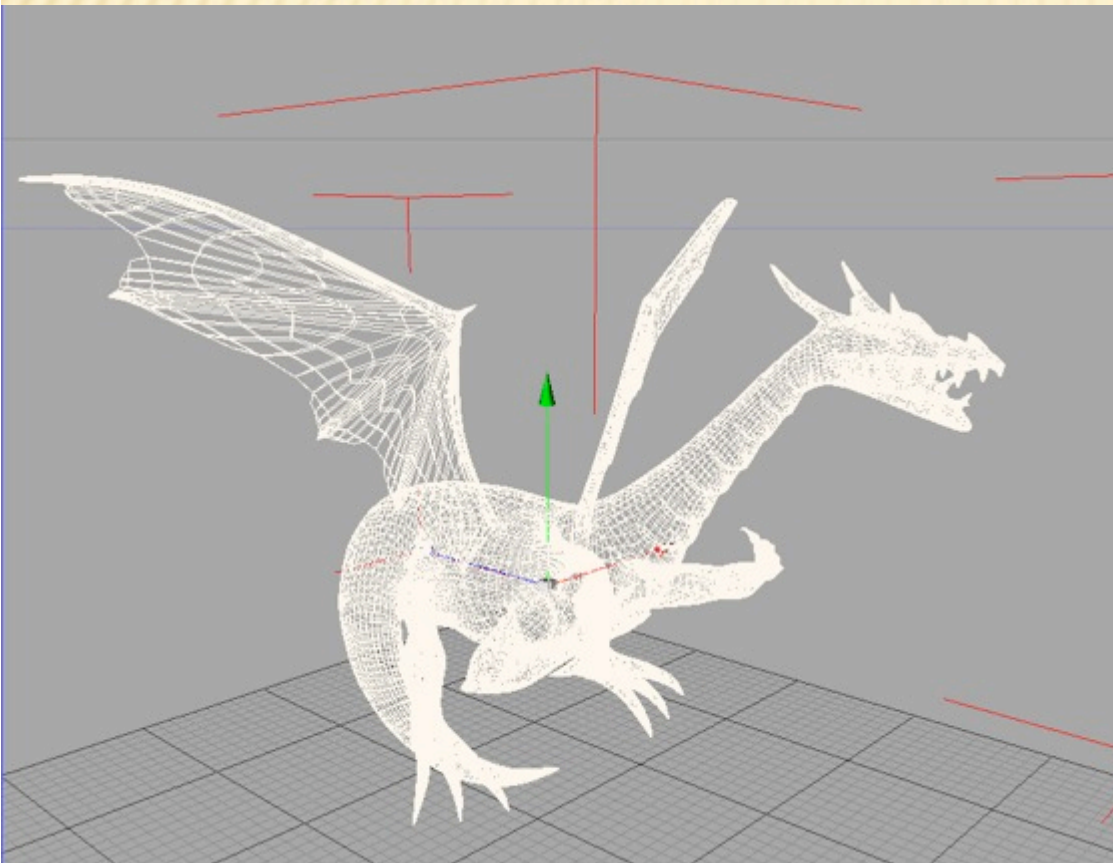
# OBJECT ORIENTED PROGRAMMING (OOP)

- ✗ Yet another way of thinking in/teaching OOP.
  - + Today, if we are “dragon behavior/motion specialists” and hired by our favorite gaming company to develop the latest game.
    - ✗ Wait... I don't know how to code in 3D yet!?  
(don't panic, be cool...)
    - ✗ Let's ask the programmers to do us a favor: give us a black box, we'll input the (x,y,z) location of the dragon's major joints, and the box will draw the dragon.
    - ✗ The programmers would go home and think: I guess the dragon's head, torso, tail, two wings and four legs will move separately. Maybe I'll need 9 smaller not-so-black boxes to implement the movements of these parts.



# OBJECT ORIENTED PROGRAMMING (OOP)

- + (Continuing with the “dragon coders” in the last slide)
  - × Each smaller box will need at least the following components: a muscle object, and a skin object. The smaller not-so-black box will draw the head/tail according to the muscle object and skin object.
  - × Suppose the “skin objects” are composed of 10 different kinds of scales, which we call it the “scale object”. Skin is drawn according to the scale objects provided.
  - × Finally, each scale is composed of multiple “polygons” (basic drawing unit of 3D objects)







## THEN WHAT?

- ✘ What have we learned from the hardware and software sides of the story?
  - + When things gets huge and complicated, we better break down the problem nicely, work as a team, and each be in charge of developing a reliable part (object).
  - + When we fit the parts (objects) together (or using those developed by our predecessors), we can create some really nice stuff.
- ✘ What tools besides “the concept of OOP” can we rely on to tackle other problems?
  - + Powerful hardware, a nice operating system, high-level programming languages, and compilers that takes care of most low level interactions with the hardware.

# A GENTLE INTRODUCTION TO THE FIELDS OF RESEARCH IN COMPUTER SCIENCE

- ✘ Instead of starting with a boring long list of research topics, let's ask ourselves, what do we want our computers to do for us?
- ✘ Basic problems that trouble us:
  - + “Run faster you stupid computer!!! ”
    - ✘ If you want to devote yourself to fixing this problem, please refer to:  
*Digital Logic, VLSI, Computer Architecture, High Speed Computing*  
(including distributed and parallel processing)
  - + “OS crashed!!! @\$%&\* )#@% !!!”
    - ✘ *Operating System, Embedded Systems*
  - + “Run/Compile you stupid Karel!!!”
    - ✘ *Programming Languages, Compilers*



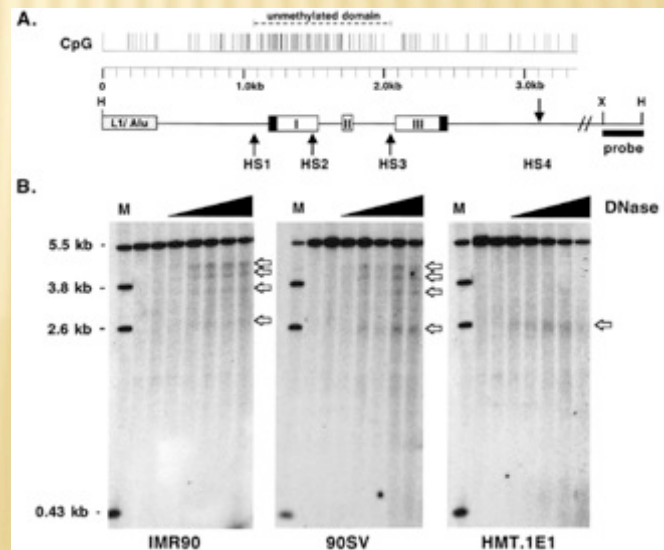
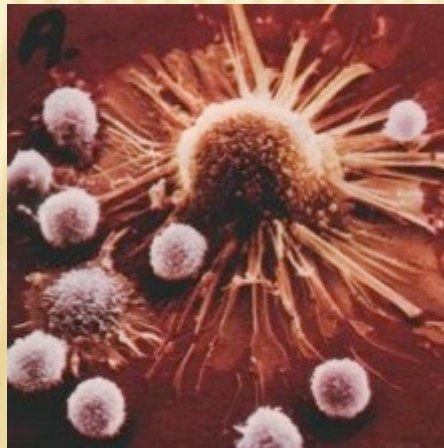
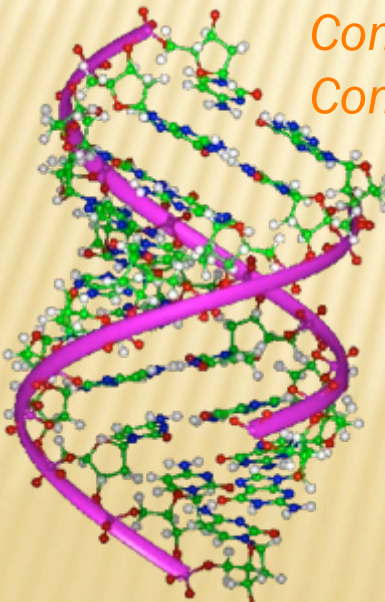
# A GENTLE INTRODUCTION TO THE FIELDS OF RESEARCH IN COMPUTER SCIENCE

- × Intermediate problems that trouble us:
  - + “Why is my (wireless) internet so slow?”
    - × *Network Design and Analysis, Wireless and Sensor Networks, Security*, probably even some *Information Theory and Coding, Graph Theories, Operating Systems*
  - + “My SPAM filter doesn’t work... Can I design a better one?”
    - × *Machine Learning*
  - + “I told my cell to call Monica, but it called mom”
    - × *Signal Processing* and *Machine Learning*, better off with knowledge in Linear Algebra, Numerical Analysis, Probability and Statistics.



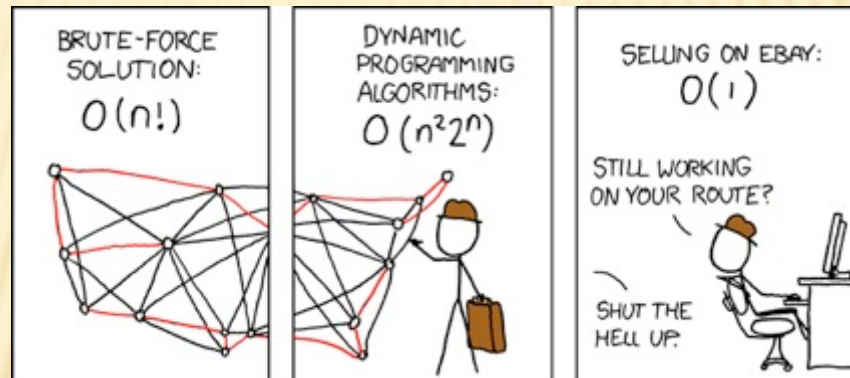
# A GENTLE INTRODUCTION TO THE FIELDS OF RESEARCH IN COMPUTER SCIENCE

- × Advanced problems that might occasionally trouble us:
  - + “I want to study science, and help create a world without cancer” (from RPCI’s commercials)
    - × There’s still a long way to go, but here’s what computer scientists can help other disciplines of research analyze their data:
    - × *Bioinformatics* (including gene analysis) , *Cognitive Science*, *Computational Chemistry*, *Computational Neuroscience*, *Computational Physics*.



# A GENTLE INTRODUCTION TO THE FIELDS OF RESEARCH IN COMPUTER SCIENCE

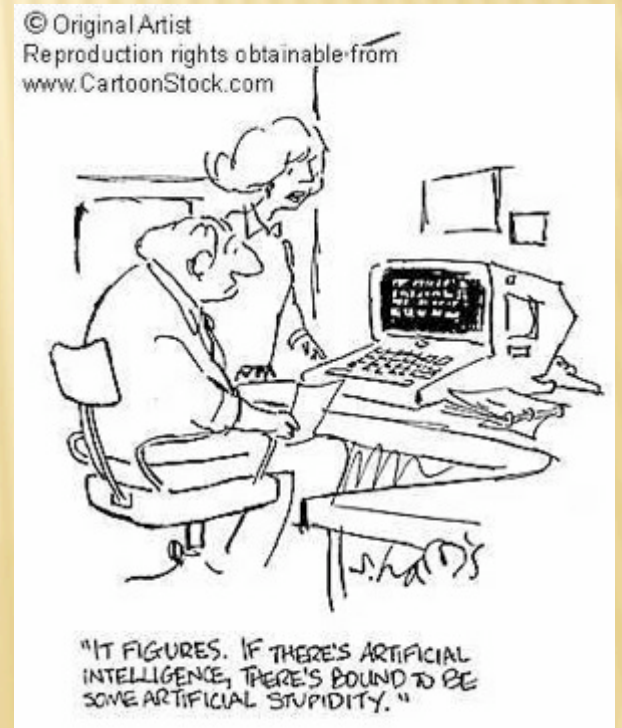
- ✗ Advanced problems that might never trouble us:
  - + Problems such as the Traveling Salesman Problem (TSP):



- ✗ Given a number of cities and the costs of travelling from any city to any other city, what is the least-cost round-trip route that visits each city exactly once and then returns to the starting city?
- ✗ *Algorithms, Analysis of Algorithms, Computational Complexity Theory, Computability Theory, Graph Theory, ... etc.*

# A GENTLE INTRODUCTION TO THE FIELDS OF RESEARCH IN COMPUTER SCIENCE

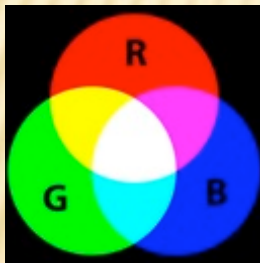
- ✘ Problems that only trouble us in our daydreams:
  - + “Can’t my computer just do everything for me? (study, take tests, drive the car, feed me...)”
    - ✘ *Artificial Intelligence, Computer Vision, Machine Learning, Pattern Recognition, Robotics.*
  - + How hard is it to teach a computer to tell between leaves and grass, sky and ocean, roads and buildings?
    - ✘ Very very hard...
    - ✘ Even the most advanced systems could only achieve around 75%-80% accuracy.



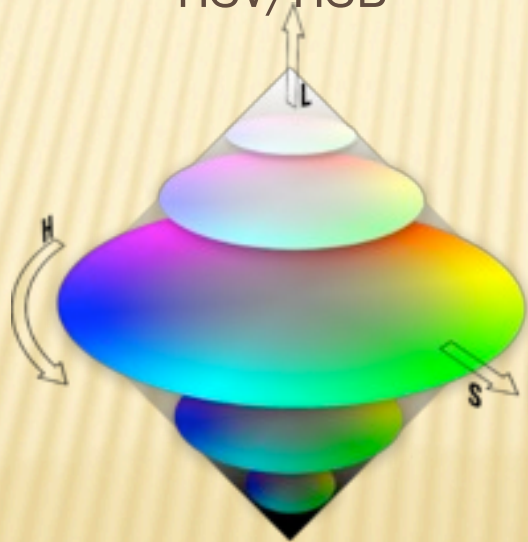
# BRIEF INTRODUCTION TO COMPUTER VISION

- ✘ Problems, problems, problems:
  - + Given an image, what color space should one use? Or should one use infrared, ultraviolet sensors instead of visible light?

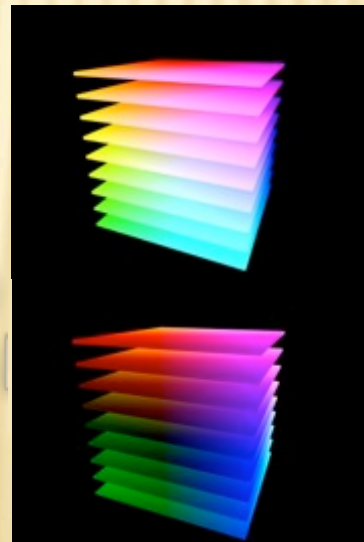
RGB



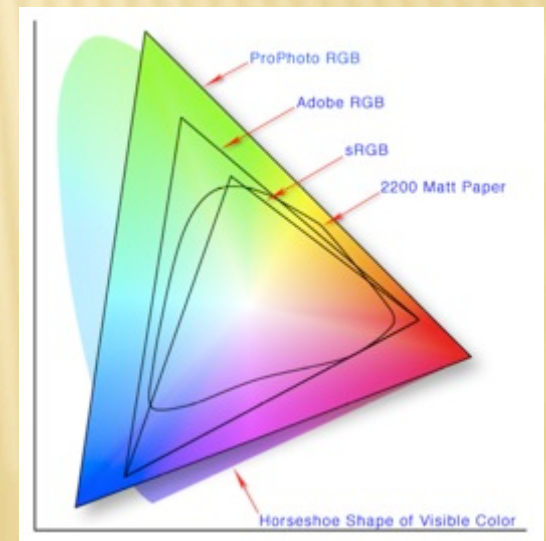
HSV/HSB



YUV



RGB v.s. visible colors



# BRIEF INTRODUCTION TO COMPUTER VISION

- + Take leaves for example, should we learn by their color? texture? shape? size!!?



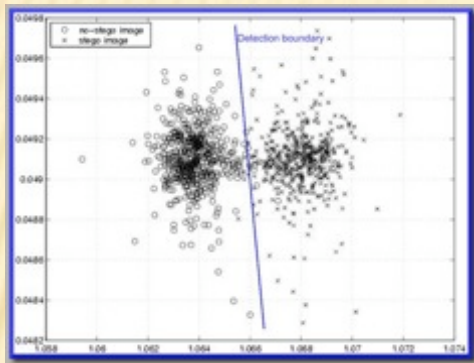
- + Since there is no “universal solution”, we usually take MANY of the features into account.
- + How are we going to weigh/normalize different features? How are we going to calculate the similarity between features?
- + *Pattern Recognition* will shed some light.



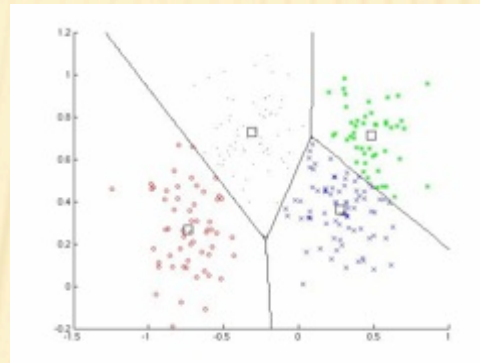
# BRIEF INTRODUCTION TO COMPUTER VISION

- + Pattern Recognition will try to learn/discriminate the distribution of different groups of objects.

LDA



K-means



SVM



- × These are just the “easier to illustrate” ones.
- × Supervised v.s. unsupervised?
- × Over learning v.s. generality?
- × Parametric v.s. Non-parametric?
- × Generative Models v.s. Discriminative methods?
- + This is just the beginning of all the struggles 😊